

## How to program the AD9834 in your DDS Development Kit

By Bruce Hall, W8BH

At the heart of your DDS development kit is the Analog Devices chip AD9834. That tiny, surface-mount piece of plastic handles all of the frequency synthesis on board. Did you know that your DDS kit has been programmed to output a signal of 12.5 MHz when it's first turned on? If you'd like to learn more, read on.

The AD9834 is a 75 MHz device, overclocked to 100 MHz. It divides its master clock by a 28 bit number, yielding an incredible 100 MHz/ $2^2$ 8 = 0.37 Hz resolution. Internally there are two frequency and two phase registers, which can be set and selected by software. The output frequency is determined by the value of the active frequency register, according to the formula:

Freq (MHz) = Register  $* 100/2^{28}$ .

Most of the time, however, we want to know the register value for a certain frequency. This equation would be:

Register = (Freq/100)\*2^28 = 2684354.56 \* Freq (in MHz)

For example, the register value for 7.040 MHz would be (7.040/100)\*2^28 = 18897856 decimal or \$01205BC0 hexadecimal. It would be great if we could just program this number into our microcontroller and then send it to the AD9834. Unfortunately it's not quite that easy! For starters, \$01205BC0 is a really big number for an 8-bit controller. Our ATmega88 can only handle numbers up to 256, which is one byte (or 2 hex digits) in size. The number we want is 4 bytes long, so we'll need to send it in four byte-sized chunks:

Send this:	\$01	(The first byte is called the MSB, 'most-significant byte')
Then this:	\$20	
Then this:	\$5B	
Then this:	\$C0	(The last byte is called the LSB, 'least-significant byte')

There is another wrinkle, too: the AD9834, for some obscure reason, wants us to embed some

bits to tell it which register it should load. That right: we have to chop up this huge number, and stuff it with a couple '01's if we want frequency register0 or a couple '10's if we want frequency register1. If you get squeamish at the sight of binary 0's and 1's, you can skip the next few paragraphs. Suffice it to say that it takes humans a while to figure out what bits to send to our AD9834. It is much easier for our AVR microcontroller.

To set a frequency register in the AD9834, we have to send it a total of 32 bits (8 bytes). These 32 bits will include the 28-bit value that we want in the register, plus 4 bits for the register address. The bits must be sent in the following order:

2 bits for register address14 upper bits for the register value2 bits for the register address (again)14 lower bits for the register value

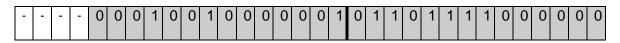
We send the register address twice because the AD9834 accepts data in 16-bit chunks. Every time we send it data, the first two bits identify what the data is for:

- 00 command follows
- 01 frequency register0 data follows
- 10 frequency register1 data follows
- 11 phase register data follows

Getting back to our 7.040 MHz example, what number do we need to enter? Here is the plan: write out the number in binary, cut it into 14 bit sections, put in '01' for register0 in the appropriate spots, and then send it to the DDS chip in byte-sized chunks.

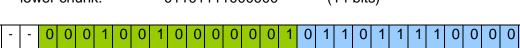
Step1: write out the number (\$01205BC0) in binary. I like to put dots between every four bits, which divide it into hex-digits. You may like to use a space, or something else.

\$1205BC0 = 0001.0010.0000.0101.1011.1100.0000 (28 bits)



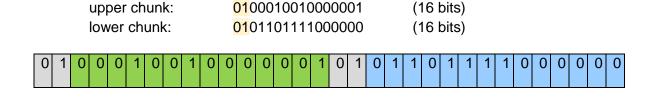
Step2: divide it into two 14-bit chunks

upper chunk:0001001000001(14 bits)lower chunk:01101111000000(14 bits)

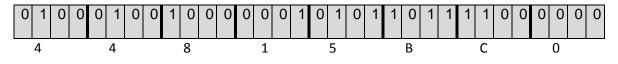


0 0

Step3: add '01' to start of each chunk, so that the DDS knows it's for register0



Step 4: group the 32 bits into four byte-sized values that the micro can handle:



Final result = \$4481.5BC0. Send four bytes: \$44, \$81, \$5B, \$C0

That's it for the binary stuff. If we send the four bytes \$44, \$81, \$5B, and \$C0 to the DDS, we will get 7.040 MHz out the other end. Diz has given us a routine to send stuff to the DDS, called Shift\_16. (Respectfully ignore the comments in the Shift\_16 code, since they are obviously a typo meant for something else).

## Finding the 12.5 MHz output

Let's try some experiments. Hook up a frequency counter to your output, and enable output with a jumper from Vcc to T+ or R+. Here is a picture of my setup. If you don't have a frequency counter handy, terminate the output with a 50 ohm resistor, extend a wire from the output towards your receiver and tune to the indicated frequency. Make sure that you are able to see RF output at 10 MHz, or whatever other frequency is indicated by your LCD.



Notice that I don't even have my LCD connected! It doesn't do anything in the following experiments – in fact, we halt the microcontroller before the LCD is initialized. Looking at a nonfunctioning LCD was bothering me, so I removed it. Now find a group of lines, near the beginning of the program, that call SHIFT\_16 several times. The last group of 3 is listed here. Add a single instruction below it, like this:

The 'halt' line forms an infinite loop. The microcontroller cannot advance beyond this point. When you run this code, your output should read 12.5 MHz. The lines above the hard stop send data to the AD9834 that specify this peculiar frequency. Why 12.5 MHz?? I dunno.

#### **Experiment #1**

It's time to send our own data. From all the binary discussion above, we know the number for an output of 7.040 MHz. Here is the code:

```
rcall exp01 ;call our experiment first, then halt
halt: rjmp halt ;hard stop.
Exp01:
; sends the value $4481.5BC0 to the DDS chip
; the corresponding DDS output frequency is 7.040 MHz
ldi temp1,$5B
ldi temp2,$C0
rcall SHIFT_16
ldi temp1,$44
ldi temp2,$81
rcall SHIFT_16
ret
```

Run it, and your frequency counter should jump to 7.040 MHz. That's nice, but it is really easy to get the bytes mixed up. I'd like to see the bytes in proper order. Here is a more user-friendly routine that takes the four input bytes from temp1 through temp4.

## **Experiment #2**

rcall exp02 ;call our experiment first, then halt halt: rjmp halt ;hard stop. Exp02: ; sends the value \$4481.5BC0 to the DDS chip

; the corresponding DDS output frequency is 7.040 MHz

```
same result as Exp01, except easier to read
;
    ldi temp1,$44
    ldi temp2,$81
    ldi temp3,$5B
    ldi temp4,$60
    rcall DDSSendData
    ret.
DDSSendData:
   sends a 4-byte value to the DDS chip,
;
;
    uses temp1 (MSB) to temp4 (LSB)
  note: this is a 32-bit value (28bit freq + 4bit register select)
;
    push templ
                              ;save MSW for now
    push temp2
    mov temp1,temp3
    mov temp2,temp4
    rcall SHIFT 16
                             ;send LSW first
    pop temp2
    pop templ
                     ;send MSW now
    rcall SHIFT 16
    ret
```

It does the exact same thing, but easier to use. If you get tired of looking at the 7.040 MHz output, try some other values. I've put an appendix at the end with a table of frequencies and their 'numbers'. For example, for 10 MHz use the numbers \$46, \$66, \$59, and \$99.

It is quite tedious doing all of the bit manipulations in Steps 1-4 above. I found myself making lots of mistakes when trying to cut and splice those 1's and 0's. Instead, we can write code to do the bit-stuffing. In our case we need to put 2 bits in front of and 2-bits in the middle of our 28-bit value. Let's do that by shifting the whole thing 2 bits to the left, and then shifting the lower 2 bytes to the right. Got that? Me neither! Here is a diagram of the steps, just like before:



After shifting everything 2 bits to the left, it will look like this:



Now shift the lower 16 bits back to the right, and it will look like this:



Now we have space for our register selection bits. To send the value to register0, our main register, we just have to put '01' at both '00' locations.



An easy way to set these two bits is with the ORI (OR-immediate) instruction. An alternative method would be to use the SBR (set bit in register) instruction. Now the 32 bits are ready, and can be send them to the DDS. Here is the code:

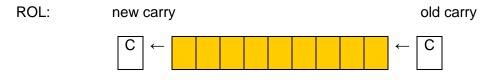
## **Experiment #3**

rcal halt: rjmp	-	;call our experiment first, then halt ;hard stop.
; the co ldi ldi ldi ldi		.5BC0 to DDS Freq Register0 frequency is 7.040 MHz
lsl rol rol lsl rol rol lsr ror lsr ror ori ori	8: the 28-bit magic numbe temp4 temp2 temp1 temp4 temp3 temp2 temp1 temp3 temp4 temp3 temp4 temp3 temp4 temp3,\$40 temp1,\$40 DDSSendData	<pre>r to Freq Register0 ;shift 1 bit left ;shift 1 bit left again ;undo shifts in LSW ;add reg0 select bits to byte3 ;add reg0 select bits to byte1 ;send Reg0 output# to DDS chip</pre>

Did you notice how we use 1 shift and 3 rotate instructions to shift everything one bit to the left? The first instruction, LSL (logical shift left), works on the least significant byte (temp4). The 'rightmost' bit, bit0, gets a 0. Bit1 gets whatever bit0 was, bit2 gets whatever bit1 was, etc. What happens to the leftmost bit, Bit7? It gets bumped off to a carry bit.



The carry bit is important, because bit7 needs to be shifted into the byte above it. The instruction that does that job is ROL (rotate left). It does the same thing as LSL, except that instead of putting a zero into bit0, it puts the carry bit.



We can extend this one-bit shift over as many bytes as we want, adding a ROL for each moresignificant byte. The two ORI instructions at the end specify that the data goes to frequency register 0. If we want to send that data to the second frequency register instead, we'd ORI with \$80 instead of \$40.

With DDSSetFreq28, calculate the number we need from the formula on page one, load it into temp1-temp4, and the desired frequency is output. The appendix lists some example numbers for the QRP calling frequencies.

Great, now it's time for another wrinkle. Diz does NOT use these 28-bit numbers to calculate frequency! And for a good reason, too. Although the number is fairly precise, it still has an inherent inaccuracy of up to 0.37 Hz. As we turn the encoder, those inaccuracies accumulate. For example, suppose that the 1 KHz number has an rounding error of +0.2 Hz. As we turn at 1 KHz increments from 7.040 to 7.080, we add 40 \* 0.2 Hz = 8 Hz to our operating frequency. The more we turn the encoder, the larger the error gets.

We can minimize the rounding error if we start with more precise numbers. Diz uses larger (x32) numbers that give us 5 more bits of precision. So instead of an accuracy of 0.37 (1E8/2^28) Hz, we now get an accuracy of 0.01 Hz (1E8/2^33). You can turn the encoder knob all day and not build up any significant error. The key is to do all computations at the higher precision, and fill the frequency register with the result/32. It is super-simple to divide by 32: just shift your result 5 bits to the right. In binary, shifting right divides by 2 and shifting left multiplies by two. Five left shifts = /32.

Let's make a new routine, using Diz' 32-bit "super" numbers instead of the regular 28-bit numbers. All we have to do is shift our supernumber 5 bits to the right (divide-by-32) and then use our old routine. Maybe something like this:

DD	SSetFreq	32idea:					
;	sends	sends the 32-bit magic number to Freq Register0					
;	divides the number by 32 (5 shifts right), then calls DDSSetFre						
	ldi	temp5,3	;do 3 bit-shifts to the right				
dd	1: lsr	templ	;shift LSB				
	ror	temp2					
	ror	temp3					
	ror	temp4	;shift MSB				
	dec	temp5	;all done?				
	brne	dd1	;no, do another bit-shift				

```
rcall DDSSetFreq28
ret
```

It works, but can be better. Look at the 28-bit routine again. The first thing it does is shift everything 2 bits to the left. Why bother going right 5 bits and then immediately back (left) 2bits? It is simpler and faster to go right by 3 bits:

```
DDSSetFreq32:
; sends the 32-bit "super" magic number to Freq Register0
    ldi temp5,3 ;do 3 bit-shifts to the right
dd0: lsr temp1
                               ;shift LSB
   ror temp2
    ror temp3
                              ;shift MSB
    ror
          temp4
          temp4
temp5
dd0
temp3
                              ;all done?
    dec
                              ;no, do another bit-shift
    brne dd0
                               ;create 2-bit space in LSW
          temp3
    lsr
    ror
          temp4
    lsr temp3
    ror temp4
    IOItemp4oritemp3,$40oritemp1,$40rcallDDSSendData; send Reg0 output# to DDS chip
    ret
```

Compare our new routine to Diz' FREQ\_OUT routine. They accomplish the exact same function, and are written very similarly. Check it out with the last experiment. The code below can use the same frequency numbers used by the main program, which are stored in the 4-byte variable rcve0.

#### **Experiment #4**

```
rcall exp04 ;call our experiment first, then halt
halt: rjmp halt ;hard stop.
Exp04:
; sends the 32-bit value $240B.7803 to DDS Freq Register0
; the corresponding DDS output frequency is 7.030 MHz
ldi temp1,$24
ldi temp2,$0B
ldi temp3,$78
ldi temp4,$03
rcall DDSSetFreq32
ret
```

That's it: you now know how to program the DDS chip. One thing I didn't cover is using the second frequency register. I have put a few routines into the source code that let you select output from either register. Having a second frequency is quite handy for things like dual VFO's/split operation, RIT/XIT, FSK, RTTY, etc.

If you try any of the above experiments with your DDS kit, don't forget to remove the code (especially the hard stop) when you're done. Your DDS kit won't work until you remove the hard stop.

# Appendix

In my examples I used numbers for 40 meters. Here are some more numbers you can try.

DDS Output	Experiment #2	Experiment #3	Experiment #4
Frequency (MHz)	Direct Entry for Reg 0	28-bit Magic Number	32-bit Magic Number
3.560	4247514E	0091D14E	123A29C7
7.030	447F72E4	011FF2E4	23FE5C91
7.040	44815BC0	01205BC0	240B7803
10.000	46665999	01999999	3333333
10.106	46777117	019DF117	33BE22E5
14.060	48FF65C9	023FE5C9	47FCB923
18.096	4B947650	02E53650	5CA6CA03
21.060	4D7A5E1B	035E9E1B	6BD3C361
24.906	4FF06656	03FC2656	7F84CAD5
28.060	51F5566C	047D566C	8FAACD9E

#### **Source Code**

;

;

Find the following lines in the original source code, near the beginning of the program. Insert new code as indicated.

ldi temp1,\$21 ;reset AD9834 and init all registers ldi temp2,\$00 rcall SHIFT 16 ;output to DDS chip ldi temp1,\$7F ;freq0 ls 14 bits ldi temp2,\$29 rcall SHIFT 16 ;output to DDS chip ldi ldi temp1,\$47 ;freq0 ms 14 bits temp2,\$FF rcall SHIFT 16 ;output to DDS chip ldi temp1,\$80 ;freq1 ls 14 bits ldi temp2,\$00 rcall SHIFT 16 ;output to DDS chip ldi temp1,\$80 ;freq1 ms 14 bits temp2,\$80 rcall SHIFT 16 ;output to DDS chip ldi temp1,\$C0 ;clear phase0 ldi temp2,\$00 rcall SHIFT 16 ;output to DDS chip ldi temp1,\$E0 ;clear phase1 temp2,\$00 ldi rcall SHIFT 16 ;output to DDS chip ldi ldi temp1,\$20 ;enable output temp2,\$00 rcall SHIFT\_16 ;output to DDS chip ; W8BH - START OF INSERTED CODE rcall exp01 ; change this to exp02, exp03, or exp04 halt: rjmp halt ;hard stop. Exp01: sends the value \$4481.5BC0 to the DDS chip the corresponding DDS output frequency is 7.040 MHz ldi temp1,\$5B ldi temp2,\$C0 rcall SHIFT 16 ldi temp1,\$44 ldi temp2,\$81 rcall SHIFT 16 ret Exp02: ; sends the value \$4481.5BC0 to the DDS chip

the corresponding DDS output frequency is 7.040 MHz ;

```
same result as Exp01, except easier to read
;
    ldi temp1,$44
    ldi temp2,$81
    ldi temp3,$5B
    ldi temp4,$60
    rcall DDSSendData
    ret
DDSSendData:
    sends a 4-byte value to the DDS chip,
;
;
    uses temp1 (MSB) to temp4 (LSB)
    note: this is a 32-bit value (28bit freq + 4bit register select)
;
    push temp1
                    ;save MSW for now
    push temp2
    mov temp1,temp3
    mov temp2,temp4
    rcall SHIFT 16
                               ;send LSW first
    pop temp2
    pop temp1
    rcall SHIFT 16
                               ;send MSW now
    ret
Exp03:
    sends the 28-bit value $0120.5BC0 to DDS Freq Register0
;
    the corresponding DDS output frequency is 7.040 MHz
    ldi temp1,$01
    ldi
         temp2,$20
    ldi temp3,$5B
    ldi temp4,$C0
    rcall DDSSetFreq28
    ret
DDSSetFreq28:
    sends the 28-bit magic number to Freq Register0
;
    lsl temp4 ;shift 1 bit left
    rol temp3
    rol
          temp2
    rol
          temp1
    lsl
          temp4
                                ; shift 1 bit left again
    rol
          temp3
    rol
          temp2
    rol
          temp1
    lsr temp3
                                ;undo shifts in LSW
    ror temp4
    lsr temp3
    ror temp4
    ori temp3,$40
ori temp1,$40
                               ;add reg0 select bits to byte3
                               ;add reg0 select bits to byte1
    rcall DDSSendData
                               ;send Reg0 output# to DDS chip
    ret
Exp04:
    sends the 32-bit value $240B.7803 to DDS Freq Register0
;
    the corresponding DDS output frequency is 7.030 MHz
;
    ldi temp1,$24
    ldi
         temp2,$0B
    ldi
         temp3,$78
    ldi temp4,$03
    rcall DDSSetFreq32
    ret
DDSSetFreq32:
; sends the 32-bit "super" magic number to Freq Register0
```

;do 3 bit-shifts to the right ldi temp5,3 dd0: lsr temp1 ;shift LSB ror temp2 ror temp3 ;shift MSB ror temp4 dec temp5 brne dd0 ;all done? ;no, do another bit-shift brne dd0 lsr temp3 ;create 2-bit space in LSW Isitemps, eredee 2 are space 1... Ls.rortemp4lsrtemp3, \$40oritemp1, \$40rcallDDSSendData, send Reg0output# to DDS chip ret DDSOutputA: set output according to frequency register 0 ; ldi temp1,\$20 ;enable output A ldi temp2,\$00 ;output to DDS chip rcall SHIFT\_16 ret DDSOutputB: set output according to frequency register 1 ; ldi temp1,\$28 ldi temp2,\$00 ;enable output B rcall SHIFT 16 ;output to DDS chip ret DDSReset: initializes the AD9834 DDS chip, clears all registers ; note: output is disabled until reset bit is cleared. ; ldi temp1,\$21 ;reset command ldi temp2,\$00 rcall SHIFT 16 ;output to DDS ;output to DDS chip ret ; W8BH - END OF INSERTED CODE rcall DEFAULT FREQ ;move default freq to buffers rcall FREQ OUT ;output freq bits to DDS chip ; FURTHER DOWN IN THE SOURCE CODE ARE THESE ORIGINAL ROUTINES ... FREQ OUT: ldi temp1,\$20 ;28 bits FREQ0 to AD9834 ldi temp2,\$00 rcall SHIFT 16 ;output to DDS chip ldi yl,low(rcve0) rcall AdjFreq ;!!W8BH - Added for IF adjustment ld temp4,v+ ;LSB ld temp3,y+ ; ld temp2,y+ ; ld temp1,y+ ;MSB

lsr temp1 ror temp2 ror temp3 ror temp4	;MSB-high ;MSB-low ;LSB-high ;LSB-low
lsr temp1 ror temp2 ror temp3 ror temp4	;MSB-high ;MSB-low ;LSB-high ;LSB-low
lsr temp1 ror temp2 ror temp3 ror temp4	;MSB-high ;MSB-low ;LSB-high ;LSB-low
lsr temp3 ror temp4 lsr temp3 ror temp4	
push temp1 push temp2 mov temp1,temp3 mov temp2,temp4	
ori temp1,0b01000000 rcall SHIFT_16 pop temp2 pop temp1	;send 14 bits
push temp1 push temp2 ori temp1,0b01000000 rcall SHIFT_16	;send 14 bits
<pre>mov temp1,temp3 mov temp2,temp4 ori temp1,0b1000000 rcall SHIFT_16</pre>	;send 14 bits
pop temp2 pop temp1 ori temp1,0b10000000 rcall SHIFT_16	;send 14 bits
ret	
;*************************************	
SHIFT_16: ;16 bit serial out msb fi push temp3	rst in temp1, then lsb in temp2
cbi PORTD,DDSenable ldi temp3,16	;FSYNC goes LOW ;16 bits bit counter
shift8: sbi PORTD,DDSdata rol temp1 brcs clockit	;set port bit ;shift dds address byte ;check for 1/0
DICS CIOCKIL	, CHECK LOI I/ U

cbi PORTD,DDSdata ;clear port bit clockit: nop cbi PORTD,DDSclock ;clock dds nop sbi PORTD,DDSclock ;decrement bit counter dec temp3 breq sox ;exit if done ; check byte counter cpi temp3,8 brne shift8 ;output more bits ;get lsb mov temp1,temp2 rjmp shift8 ;write data bits SOX: sbi PORTD,DDSenable ;FSYNC goes HIGH pop temp3 ret